

Value	Unit	Profile 0	Profile 1	Profile 2	Profile 3	Profile 4	Profile 5	Profile 6	Profile 7	Profile 8	Profile 9
From database Ver.	Version	1	1	1	1	2 / 6	2 / 6	2 / 6	2	2	2
Profile Date	WEEKYEAR	1018	1018	1018	1018	1018 / 0720	1018 / 0720	1018 / 0720	1118	1218	1218
From Software version *1	Version	3,25	3,25	3,25	3,26	3,27 / 3,43	3,27 / 3,43	3,27 / 3,43	3,28	3,30	3,30
Tested on	1002/1145/both	1145	1145	1145	both	1145	1145	1145	1145	1145	1145
DIP - switch	O = OFF, I = ON	0000 0000	0000 000I	0000 00IO	0000 00II	0000 0100	0000 010I	0000 0110	0000 011I	0000 1000	0000 100I
Pol Pairs	[pol pairs]	3	2	2	2	2	2	2	2	2	2
Max. Start Current	[Arms]	4	3	4	7	4	4	5	5	4	5
Max. Run Current	[Arms]	8	5	8	14	8	8	10	11	8	10
Stator resistance	[Ohm] pr. winding	0,934	1,36	1,02	0,25	0,703	0,37	0,84	0,37	0,305	0,665
Inductance (Lq) (Lq <= 2xLd)	[mH]	12,2 @6A	9,93 @5A	20,6 @5A	5,00 @9A	9,30 @5A	14,82 @5A	13,83 @7A	4,04 @16A	6,57 @5A	10,01 @8A
Flux	[Wb]	0,128	0,106	0,749	0,17	0,118	0,0919	0,1356	1,824	0,102	0,1314
Min. Speed	[rpm]	1000	2400	900	900	1000	1000	1600	720	1200	1600
Max. Speed	[rpm]	7200	7200	6000	7200	7200	6600	7200	7200	7200	7200
Accelleration Speed	[rpm/s]	300	300	300	300	300	300	300	50	300	300
Decellerate Speed	[rpm/s]	300	300	300	300	300	300	300	50	300	300

Value	Unit	Profile 10	Profile 11	Profile 12 *2	Profile 13	Profile 14	Profile 15 *2	Profile 16	Profile 17	Profile 18 *2	Profile 19
From database Ver.	Version	2	2	2	3	3	4	4	4	5	6
Profile Date	WEEKYEAR	0219	0219	0219	1219	1219	0220	0220	0220	0520	0920
From Software version *1	Version	3,31	3,33	3,33	3,38	3,38	3,40	3,40	3,40	3,42	3,44
Tested on	1002/1145/both	1145	both	1145	1145	both	1145	1145	1145	1145	1002
DIP - switch	O = OFF, I = ON	0000 IOIO	0000 IOII	0000 IIOO	0000 IIOI	0000 IIIO	0000 IIII	000I 0000	000I 000I	000I 00IO	000I 00II
Pol Pairs	[pol pairs]	2	2	2	3	2	3	3	3	3	2
Max. Start Current	[Arms]	4	7	4	3	6	4	4	1	2	4
Max. Run Current	[Arms]	8	14	11	6	14	9	10	6	6,5	14,7
Stator resistance	[Ohm] pr. winding	0,85	0,251	0,72	0,766	0,428	0,576	0,465	0,735	No data	0,395
Inductance (Lq) (Lq <= 2xLd)	[mH]	10,40 @3,8A	5,00 @9A	No data	11,99 @5A	10,01 @8A	No data	7,74 @5A	9,7@no load	No data	8,62
Flux	[Wb]	0,6	0,1702	No data	0,1286	0,131	No data	0,111	0,131	No data	0,21
Min. Speed	[rpm]	1080	900	900	1000	900	900	600	600	2100	1000
Max. Speed	[rpm]	7200	7200	7200	7200	7200	7200	7200	6000	7200	7200
Accelleration Speed	[rpm/s]	300	300	300	100	100	100	100	100	100	100
Decellerate Speed	[rpm/s]	300	300	300	100	100	100	100	100	100	100

	In Modbus	On label	Spreadsheet	Example
*1 : Software description.	3.31	3.31	3.31	if you read Version 3.317 in modbus or on the label, you can translate this number to the software version 3.31 in this spreadsheet.
	3.31x	3.31x	3.31	
	3.31xx	3.31xx	3.31	
	3.31xxx	3.31xxx	3.31	

*2 : Some values not available in datatsheet.
LS Control tunet values.

Tested on 1145 or 1002
X : Means that LS Control or a customer has tested the motor on the SpeedControl 1145 or 1002 or both.
Blank : Means that the motor has not been tested, but if the motor is designed for the given inverter type (1 phase / 3 phase or both), it will work, but it could need fine tuning.

Changes on existing profiles:
 - From version 3.42x - Profile 4, 5 and 6 retuned for better performance

Value	Unit	Profile 20	Profile 21 *2	Profile 22	Profile 23 *2	Profile 24	Profile 25 *2	Profile 26	Profile 27	Profile 28
From database Ver.	Version	6	6	7	7	8	8	9	9	9
Profile Date	WEEKYEAR	0920	0920	5220	5220	2321	2321	3721	3721	3921
From Software version *1	Version	3,44	3,44	3,45	3,45	3,47	3,47	3,48	3,48	3,48
Tested on	1002/1145/both	1145	1145	both	1002	1145	Special 1145	1002	1002	1145
DIP - switch	O = OFF, I = ON	OOOI OIOO	OOOI OIOI	OOOI OIIO	OOOI OIII	OOOI IOOO	OOOI IOOI	OOOI IOIO	OOOI IOII	OOOI IIOO
Pol Pairs	[pol pairs]	2	2	2	2	2	2	2	2	3
Max. Start Current	[Arms]	4	4	7	5	4	0,7	5	5	4
Max. Run Current	[Arms]	10	10	16	16	9	1,5	16	16	10
Stator resistance	[Ohm] pr. winding	0,65	0,81	0,251	0,36	0,285	No data	0,436	0,289	0,677
Inductance (Lq) (Lq <= 2xLd)	[mH]	18,3	26,4 @6A	5,00 @9A	No data	8,14 @ 5A	No data	12,2 @10A	8,1 @15A	10,7 @5A
Flux	[Wb]	0,422	No data	0,17	0,537	0,1425	No data	No data	No data	0,1351
Min. Speed	[rpm]	600	1200	900	900	1000	1200	720	900	900
Max. Speed	[rpm]	7200	7200	7200	7200	7200	4500	6660	6660	7200
Accelleration Speed	[rpm/s]	100	100	100	100	100	100	100	100	100
Decellerate Speed	[rpm/s]	100	100	100	100	100	100	100	100	100

Value	Unit									
From database Ver.	Version									
Profile Date	WEEKYEAR									
From Software version *1	Version									
Tested on	1002/1145/both									
DIP - switch	O = OFF, I = ON									
Pol Pairs	[pol pairs]									
Max. Start Current	[Arms]									
Max. Run Current	[Arms]									
Stator resistance	[Ohm] pr. winding									
Inductance (Lq) (Lq <= 2xLd)	[mH]									
Flux	[Wb]									
Min. Speed	[rpm]									
Max. Speed	[rpm]									
Accelleration Speed	[rpm/s]									
Decellerate Speed	[rpm/s]									

	In Modbus	On label	Spreadsheets	Example
*1 : Software description.	3.31	3.31	3.31	if you read Version 3.317 in modbus or on the label, you can translate this number to the software version 3.31 in this spreadsheet.
	3.31x	3.31x	3.31	
	3.31xx	3.31xx	3.31	
	3.31xxx	3.31xxx	3.31	

***2 :** Some values not available in datatsheet. LS Control tunet values.

Tested on 1145 or 1002
X : Means that LS Control or a customer has tested the motor on the SpeedControl 1145 or 1002 or both.
Blank : Means that the motor has not been tested, but if the motor is designed for the given inverter type (1 phase / 3 phase or both), it will work, but it could need fine tuning.

Changes on existing profiles:
 - From version 3.42x - Profile 4, 5 and 6 retuned for better performance